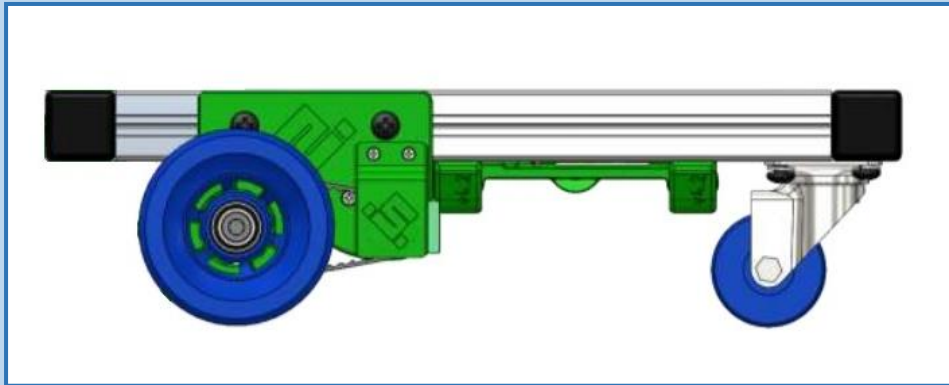
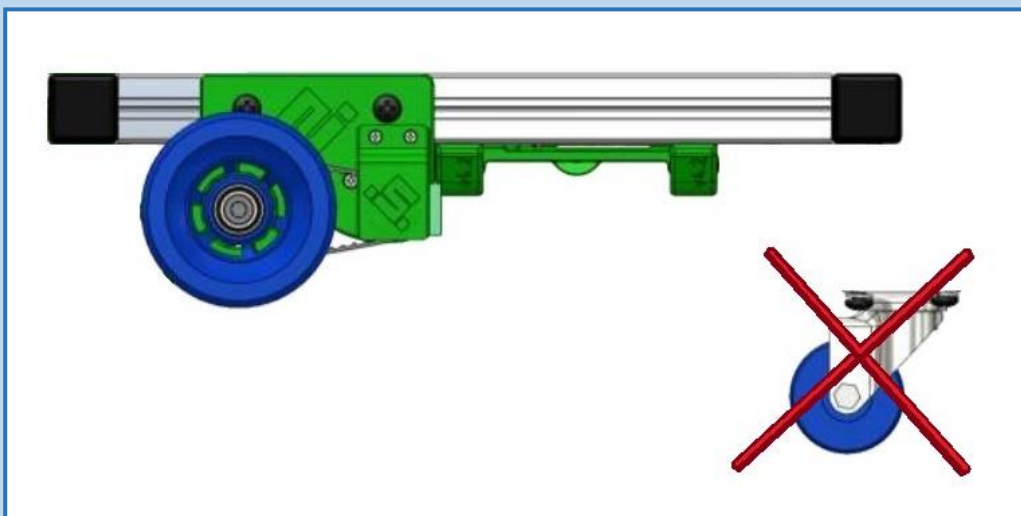


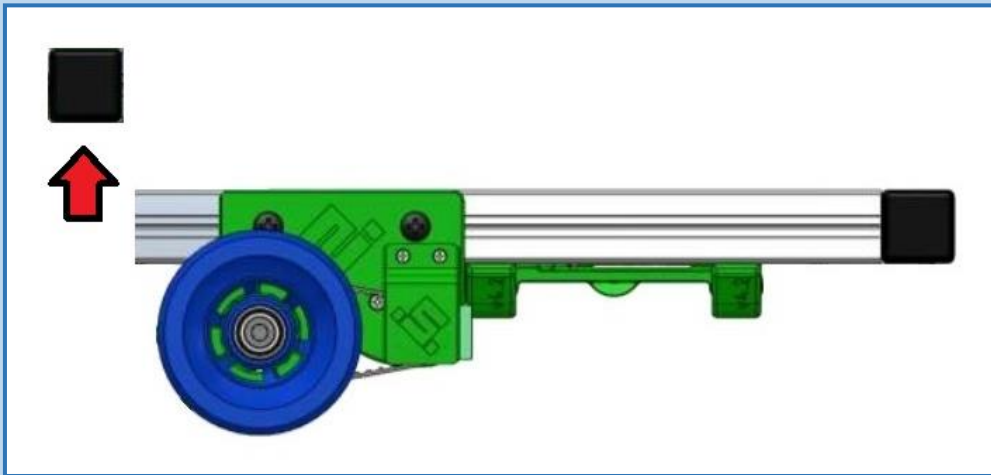
1. Start with Standard Setup



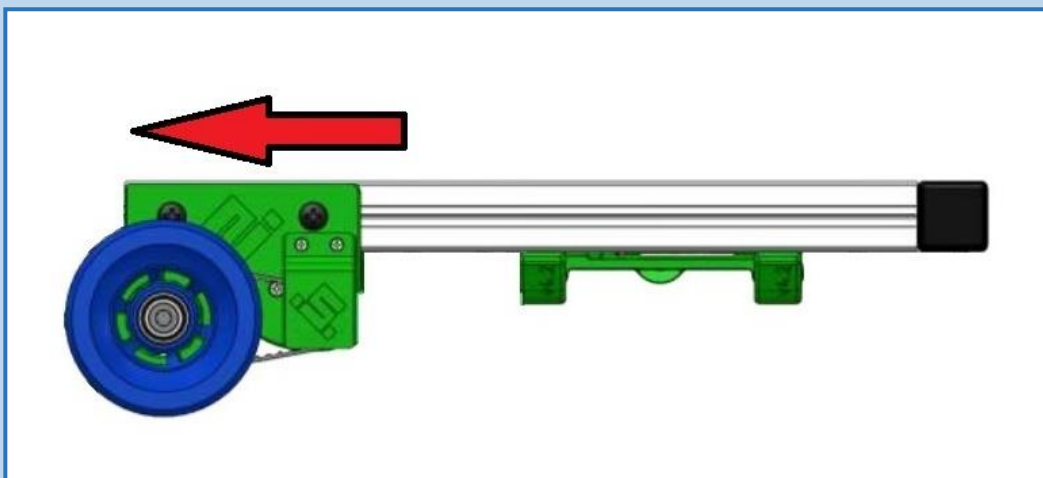
2. Remove Caster Wheels



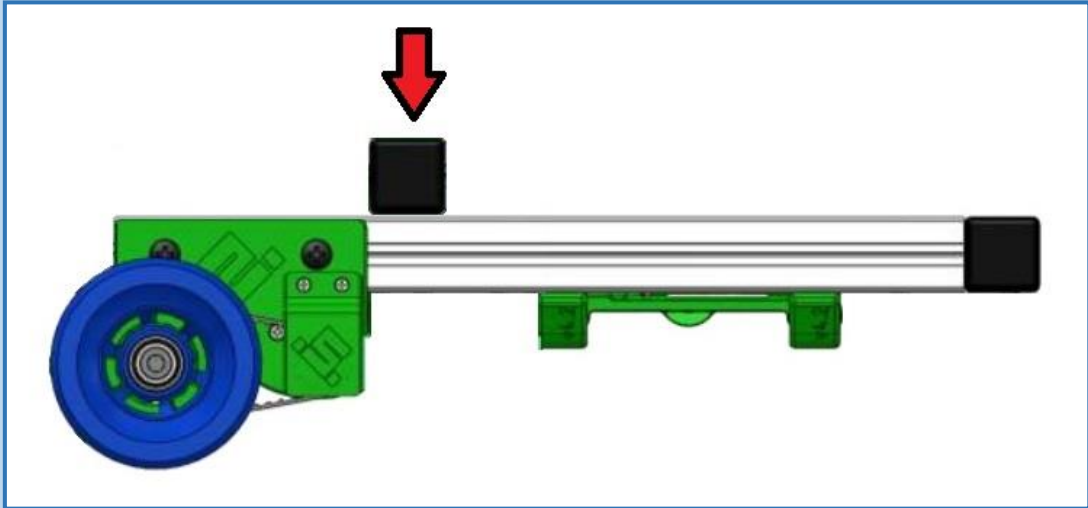
3. Remove Framing Rail



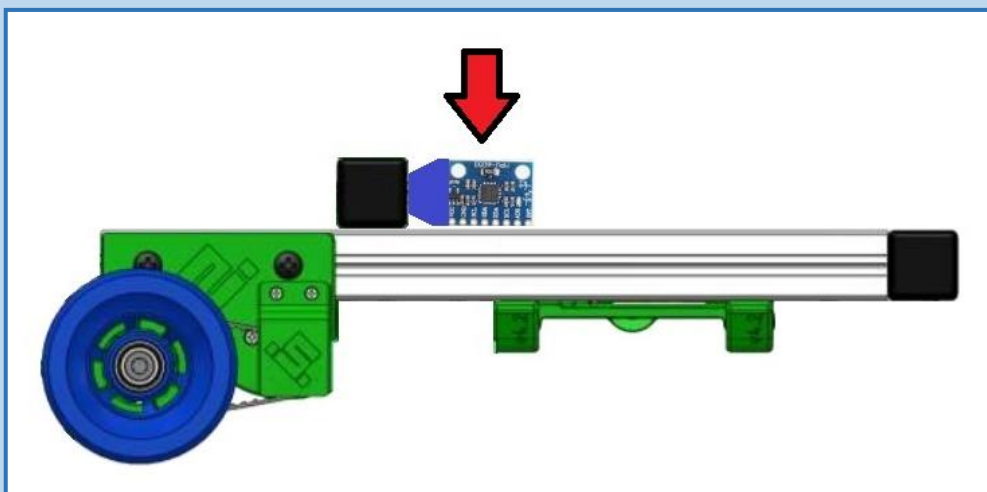
4. Move Wheels & Parts till End



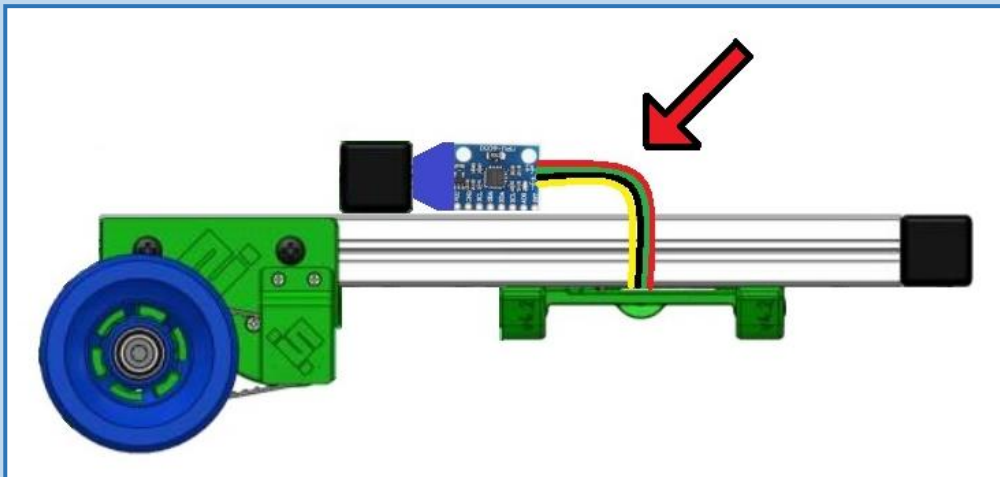
5. Mount the Framing Rail
Removed Before



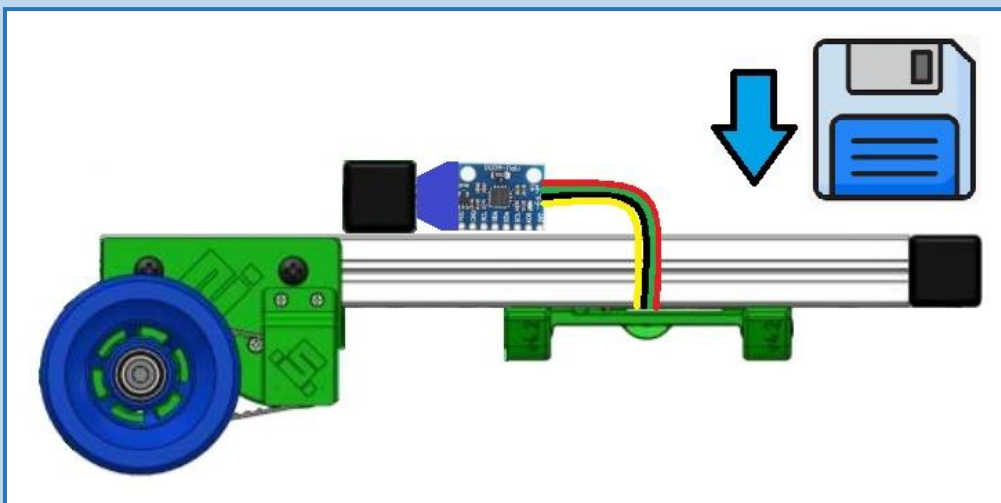
6. Mount MPU6050 Accelerometer and
Gyroscope Sensor with 3D Printed Part
Holder



7. Connect Cables between MPU6050 and Raspberry Pi



8. Download “Self-Balanced Robot” Software to Raspberry Pi



9. Turn on Scuttle Robot and
Let It Stand on 2 Wheels

